The Unified Transform Method: An unexpected extension of classical works of d'Alembert, Fourier and Laplace

Athanasios S. Fokas

Department of Applied Mathematics and Theoretical Physics University of Cambridge

and

Mathematics Research Center Academy of Athens

under the auspices of "Greece 2021 Mathematical Legacy Programme"



UNIVERSITY OF CAMBRIDGE GIANNA ANGELOPOULOS PROGRAMME FOR SCIENCE, TECHNOLOGY AND INNOVATION 1747, d' Alembert and Euler: Separation of Variables

- 1807, Fourier: Transforms
- 1814, Cauchy: Analyticity
- 1828, Green: Green's Representations
- 1845, Kelvin: Images



- A.S. Fokas, A Unified Approach to Boundary Value Problems, CBMS-NSF, SIAM (2008)
- A.S. Fokas and E.A Spence, Synthesis as Opposed to Separation of Variables, SIAM Review 54, 291-324 (2012)
- B. Deconinck, T. Trogdon and V. Vasan, The Method of Fokas for Solving Linear Partial Differential Equations, SIAM Review 56, 159-186 (2014)
- A.S. Fokas and E. Kaxiras, Modern Mathematical Methods for Scientists and Engineers, in press

Linear Evolution PDEs on the Half-Line Classical methods

The heat equation

$$u_t = u_{xx}, \quad 0 < x < \infty, \quad 0 < t < T, \quad T > 0,$$

Initial condition:

$$u(x,0) = u_0(x), \quad 0 < x < \infty,$$

Boundary condition:

$$u(0,t) = g_0(t), \ \ 0 < t < T.$$

Classical Sine Transform method:

$$\mathsf{PDE}[u(x,t)] \xrightarrow{ST} \mathsf{ODE}[\hat{u}(\lambda,t)] \xrightarrow{Solve} \hat{u}(\lambda,t) \xrightarrow{ST} u(x,t)$$

The classical solution:

$$u(x,t) = \frac{2}{\pi} \int_0^\infty e^{-\lambda^2 t} \sin(\lambda x) \Big[\int_0^\infty \sin(\lambda \xi) u_0(\xi) d\xi - \lambda \int_0^t e^{\lambda^2 s} g_0(s) ds \Big] d\lambda.$$

Disadvantages of the Traditional Transforms

- 1. Lack of uniform convergence at the boundaries (for inhomogeneous boundary conditions).
- 2. Not straightforward to verify that the solution representation actually solves the given BVP.
- 3. Not suitable for numerical computations.
- 4. Requires separability of PDE-domain-BCs. For example, cannot be applied to

$$\int_0^\infty K(x,t)u(x,t)dx=g(t).$$

- 5. Difficult to obtain appropriate transform.
- Traditional transforms exist only for a very limited class of problems.

There are no x-transforms for the diffusion-convection equation

$$u_t = u_{xx} + u_x,$$

or the Stokes (written by Sir George Stokes)

$$u_t + u_x + u_{xxx} = 0.$$

```
"Green + Fourier + Cauchy"
```

Three ingredients:

- 1. Global Relation equation coupling transforms of boundary values.
- 2. Integral representation solution given as integral of *transforms* of boundary values. ("Green + Fourier").
- 3. Symmetries which leave transforms of the boundary values invariant. Use information given by 1 to *either* find unknown boundary values *or* their contributions to 2.

In all but the simplest cases need to consider transforms of boundary values as functions in $\mathbb C$ ("Cauchy").

The heat equation via the Fokas Method

The heat equation can be written as a family of divergence forms:

$$\left(e^{-i\lambda x+\lambda^2 t}u\right)_t - \left(e^{-i\lambda x+\lambda^2 t}(u_x+i\lambda u)\right)_x = 0, \quad \lambda \in \mathbb{C}.$$

Green's Theorem:
$$\int_{\partial\Omega} e^{-i\lambda x + \lambda^2 t} [udx + (u_x + i\lambda u)dt] = 0.$$

For the half line the Global Relation is

$$e^{\lambda^2 t} \hat{u}(\lambda,t) = \hat{u}_0(\lambda) - ilde{g}_1(\lambda^2,t) - i\lambda ilde{g}_0(\lambda^2,t), \quad \mathrm{Im}\lambda \leq 0,$$

where

$$\hat{u}(\lambda,t) = \int_0^\infty e^{-i\lambda x} u(x,t) dx, \qquad \hat{u}_0(\lambda) = \int_0^\infty e^{-i\lambda x} u_0(x) dx, \quad \mathrm{Im}\lambda \leq 0,$$

 $\tilde{g}_j(\lambda,t) = \int_0^t e^{\lambda \tau} g_j(\tau) d\tau, \quad \mathrm{with} \ g_1(t) = u_x(0,t), \ g_0(t) = u(0,t), \ t > 0.$

First use of the GR:

$$u(x,t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\lambda x - \lambda^2 t} \hat{u}_0(\lambda) d\lambda + \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\lambda x - \lambda^2 t} \left[\tilde{g}_1(\lambda^2,t) - i\lambda \tilde{g}_0(\lambda^2,t) \right] d\lambda.$$

The second integral can be deformed to the curve ∂D^+ , defined by $\operatorname{Re}(\lambda^2) = 0$, $\operatorname{Im} \lambda > 0$.

 $\pi/4$

7/4

Second use of the GR:

$$e^{\lambda^2 t} \hat{u}(-\lambda,t) = \hat{u_0}(-\lambda) - ilde{g}_1(\lambda^2,t) + i\lambda ilde{g}_0(\lambda^2,t), \ \ {\sf Im}\lambda \geq 0$$

The solution takes the form

$$u(x,t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\lambda x - \lambda^2 t} \hat{u}_0(\lambda) d\lambda - \frac{1}{2\pi} \int_{\partial D^+} e^{i\lambda x - \lambda^2 t} \left[\hat{u}_0(-\lambda) + 2i\lambda \tilde{g}_0(\lambda^2,t) \right] d\lambda.$$

Also, we can replace \tilde{g}_0 with $G_0(\lambda^2) = \int_0^1 e^{\lambda^2 s} g_0(s) ds$, $\lambda \in \mathbb{C}$. Consistent with the Ehrenpreis Principle:

$$u(x,t) = \int_{L} e^{i\lambda x - \lambda^{2}t} d\rho(\lambda).$$

Numerical Implementation

Consider the heat equation with

$$u_0(x) = e^{-ax}, g_0(t) = \cos(bt), \quad a > 0, b > 0.$$

Then,

$$u(x,t) = \int_{L} e^{i\lambda x - \lambda^{2}t} \left[\frac{1}{i\lambda + a} + \frac{1}{i\lambda - a} + i\lambda \left(\frac{1}{\lambda^{2} + ib} + \frac{1}{\lambda^{2} - ib} \right) \right] \frac{d\lambda}{2\pi}$$
$$- \int_{L} e^{i\lambda x} i\lambda \left(\frac{e^{ibt}}{\lambda^{2} + ib} + \frac{e^{-ibt}}{\lambda^{2} - ib} \right) \frac{d\lambda}{2\pi}.$$



de Barros, Colbrook and Fokas. A hybrid analytical-numerical method for solving advection-dispersion problems on a half-line. International Journal of Heat and Mass Transfer. (2019)

The last term can be evaluated explicitly, via Residue theory:

$$u(x,t) = \int_{L} e^{i\lambda x - \lambda^{2}t} V(\lambda;a,b) \frac{d\lambda}{2\pi} + e^{-x\sqrt{\frac{b}{2}}} \cos\left(bt - x\sqrt{\frac{b}{2}}\right),$$

with $V(\lambda; a, b) = \frac{1}{i\lambda+a} + \frac{1}{i\lambda-a} + i\lambda \left(\frac{1}{\lambda^2+ib} + \frac{1}{\lambda^2-ib}\right)$. Verification: Evaluating the above equation at x = 0 yields

$$u(0,t) = \int_{L} e^{-\lambda^{2}t} V(\lambda;a,b) \frac{d\lambda}{2\pi} + \cos(bt) = \cos(bt).$$

By deforming the contour *L* to the real line and observing that $V(\lambda; a, b)$ is an odd function of λ , the above integral vanishes. Evaluating the previous equation at t = 0 yields

$$u(x,0) = \int_C e^{i\lambda x} \left(\frac{1}{i\lambda + a} + \frac{1}{i\lambda - a}\right) \frac{d\lambda}{2\pi}.$$

Then, Cauchy's theorem yields

$$u(x,0) = \frac{2\pi i}{2\pi} e^{i(ia)x} \frac{1}{i} = e^{-ax}$$

Solutions of linear second and third order PDES

Heat Equation - Half Line Dirichlet Problem



Fokas & Kaxiras, Modern Mathematical Methods for Scientists and Engineers,

in press

Heat Equation - Half Line Oblique Robin Problem

$$\begin{cases} u_t = u_{xx}, & x \in (0, +\infty), \ t \in (0, T), \\ u(x,0) = xe^{-4x}, & x \in (0, +\infty) \\ u_t(0,t) - 2u_x(0,t) + u(0,t) = \sin(5t), & t \in (0, T). \end{cases}$$

Solution:

$$u(x,t) = \int_L V(\lambda,x,t) \frac{d\lambda}{2\pi} + v(x,t),$$

where

$$V(\lambda, x, t) = e^{i\lambda x - \lambda^2 t} \left(\frac{\frac{10i\lambda}{\lambda^4 + 25} + \frac{(\lambda - i)^2}{(\lambda + 4i)^2}}{(\lambda + i)^2} + \frac{1}{(4 + i\lambda)^2} \right),$$

and

$$v(x,t) = e^{-\sqrt{\frac{5}{2}x}} \frac{\left(\sqrt{10}+1\right) \sin\left(5t-\sqrt{\frac{5}{2}x}\right) - \left(\sqrt{10}+5\right) \cos\left(5t-\sqrt{\frac{5}{2}x}\right)}{\left(\sqrt{10}+6\right)^2}$$

Heat Equation - Half Line Oblique Robin Problem

Illustration of the solution:



Heat Equation - Finite Interval General Dirichlet Problem

$$\begin{cases} u_t = u_{xx}, & x \in (0, L), \ t \in (0, T), \\ u(x, 0) = u_0(x), & x \in (0, L) \\ u(0, t) = g_0(t), & u(L, t) = h_0(t), & t \in (0, T). \end{cases}$$
$$u(x, t) = \int_{-\infty}^{\infty} e^{i\lambda x - \lambda^2 t} \hat{u}_0(\lambda) \frac{d\lambda}{2\pi}$$
$$- \int_{\partial D^+} \frac{2e^{-\lambda^2 t}}{e^{i\lambda L} - e^{-i\lambda L}} \bigg\{ \sin(\lambda x) \Big[ie^{i\lambda L} \hat{u}_0(\lambda) - 2\lambda \tilde{h}_0(\lambda^2 t) \Big] \\+ \sin[\lambda(L-x)] \Big[i\hat{u}_0(-\lambda) - 2\lambda \tilde{g}_0(\lambda^2 t) \Big] \bigg\} \frac{d\lambda}{2\pi}$$

Heat Equation - Finite Interval Specific example on Dirichlet Problem



The wave equation

$$u_{tt} - u_{xx} = 0, \qquad x > 0, \quad t > 0.$$

Dirichlet conditions

$$u(x,0) = u_0(x),$$
 $u_t(x,0) = u_1(x),$ $x > 0,$
 $u(0,t) = g_0(t),$ $t > 0.$

Solution in the Fourier plane:

$$u(x,t) = \int_{-\infty}^{\infty} e^{ikx} \left[\frac{\sin(kt)}{k} \hat{u}_1(k) + \cos(kt) \hat{u}_0(k) \right] \frac{dk}{2\pi} - \int_{-\infty}^{\infty} e^{ikx} \left[\frac{\sin(kt)}{k} \hat{u}_1(-k) + \cos(kt) \hat{u}_0(-k) + 2ik \check{g}_0(k,t) \right] \frac{dk}{2\pi},$$

Solution in the physical plane:

$$u(x,t) = rac{1}{2}u_0(x+t) + rac{1}{2}\int_{|x-t|}^{x+t}u_1(\xi)d\xi + egin{cases} rac{1}{2}u_0(x-t), & x>t, \ g_0(t-x) - rac{1}{2}u_0(t-x), & x$$

Laplace equation on a polygon

Let u(x, y) satisfy the Laplace equation in the interior of a convex polygon characterized by $z_1, ..., z_n$. Then $u_z(z)$ satisfies

$$u_z(z) = \frac{1}{2\pi} \sum_{j=1}^n \int_{I_j} e^{i\lambda z} \hat{u}_j(\lambda) d\lambda, \qquad u_z = \frac{1}{2} (u_x - iu_y), \qquad z = x + iy,$$

where $\hat{u}_j(\lambda)$ is defined by

$$\hat{u}_j(\lambda) = \int_{z_j}^{z_{j+1}} e^{-i\lambda z} \left[\frac{\partial u}{\partial N} + \lambda u \frac{dz}{ds} \right] ds, \quad j = 1, ..., n, \qquad \lambda \in \mathbb{C}.$$

and the rays $\{l_j\}_1^n$ are defined by

$$l_j = \rho e^{i\theta_j}, \quad 0 < \rho < \infty, \quad \theta_j = -\arg(z_{j+1} - z_j), \quad j = 1, ..., n.$$

Furthemore, the following GR is valid:

$$\sum_{j=1}^n \hat{u}_j(\lambda) = 0, \qquad \lambda \in \mathbb{C}.$$

Numerical approach

The numerical solution of the global relation for determining the unknown boundary values involves the following two steps.

1. Expand the functions $\{u_j\}_1^n$ and $\left\{\frac{\partial u_j}{\partial w}\right\}_1^u$ in terms of N basis functions denoted by $\{S_l(t)\}_0^{N-1}$:

$$u_j \approx \sum_{l=0}^{N-1} a_l^j S_l(t), \quad \frac{\partial u_j(t)}{\partial \omega} \approx \sum_{l=0}^{N-1} b_l^j S_l(t), \quad j=1,2,\ldots,n.$$

Choosing S_I to be the Legendre polynomials, denoted by P_I , the relevant Fourier transform can be computed explicitly,

$$\hat{P}_{l}(\lambda) = \int_{-1}^{1} e^{-i\lambda t} P_{l}(t) dt = i \sum_{k=0}^{l} \frac{(l+k)!}{(l-k)!k!} \left[\frac{(-1)^{l+k} e^{i\lambda} - e^{-i\lambda}}{(2i\lambda)^{k+1}} \right]$$

2. The global relation and its complex conjugate yield two equations involving the constants a_l^j and b_l^j . By evaluating these equations at appropriately chosen values of λ called *collocation points*, we can solve for the unknown coefficients.

The case of the Square

Consider the Laplace equation in the interior of the square with corners

$$z_1 = -1 + i$$
, $z_2 = -1 - i$, $z_3 = 1 - i$, $z_4 = 1 + i$.

The approximate global relation yields

$$\hat{u}_1(\lambda) + \hat{u}_2(\lambda) + \hat{u}_3(\lambda) + \hat{u}_4(\lambda) = 0, \quad \lambda \in \mathbb{C},$$

where

$$\begin{split} \hat{u}_{1}(\lambda) &\approx -e^{i\lambda} \sum_{l=0}^{N-1} \left[i\lambda a_{1}^{l} \hat{P}_{l}(\lambda) + b_{1}^{l} \hat{P}_{l}(\lambda) \right], \\ \hat{u}_{2}(\lambda) &\approx e^{-\lambda} \sum_{l=0}^{N-1} \left[\lambda a_{2}^{l} \hat{P}_{l}(-i\lambda) + b_{2}^{l} \hat{P}_{l}(-i\lambda) \right], \\ \hat{u}_{3}(\lambda) &\approx e^{-i\lambda} \sum_{l=0}^{N-1} \left[i\lambda a_{3}^{l} \hat{P}_{l}(\lambda) + b_{3}^{l} \hat{P}_{l}(\lambda) \right], \\ \hat{u}_{4}(\lambda) &\approx e^{\lambda} \sum_{l=0}^{N-1} \left[-\lambda a_{4}^{l} \hat{P}_{l}(-i\lambda) + b_{4}^{l} \hat{P}_{l}(-i\lambda) \right]. \end{split}$$

For a given side, choose λ in such a way that for the given side we obtain the usual Fourier transform of the Legendre functions, whereas the contribution from the remaining sides vanishes as $\lambda \to \infty$ (it can be shown that for a *convex* polygon such a choice is always possible). In fact we choose to be on the "complement" of the rays l_j .

- ▶ side 1. Multiply the approximate global relation by $e^{-i\lambda}$ and then let $\lambda = -i\rho$, $\rho > 0$.
- side 2. Multiply by e^{λ} and then let $\lambda = -\rho$, $\rho > 0$.
- ▶ side 3. Multiply by $e^{i\lambda}$ and then let $\lambda = i\rho$, $\rho > 0$.

► side 4. Multiply by $e^{-\lambda}$ and then let $\lambda = \rho$, $\rho > 0$. For ρ we can use the discrete values $\rho = \frac{R}{M}m$, m = 1, 2, ..., M, R > 0, where R/M determines how close are the collocation points.

Numerical experiments suggest the following rules for low condition number:

$$R = 2M, \qquad M = Nn.$$

Dirichlet-to-Neumann map: Knowing a_j^l and evaluating the *Legendre expansion* on the *collocation points* in the approximate global relation we can determine the coefficients b_j^l numerically. For real-valued u, we also evaluate the Schwartz conjugate of the global relation at the complex conjugates of the suggested collocation points. The result is an overdetermined linear system, which is inverted in the least squares sense.



The plots above show the output of this procedure. The left panel shows the convergence of the method and the right panel typical computed boundary values. We see exponential convergence, since this simple example has no corner singularities.

Modified Helmholtz equation on the quarter plane

$$\begin{cases} u_{xx}(x,y) + u_{yy}(x,y) - u(x,y) = 0, & x > 0, y > 0, \\ u_x(0,y) = e^{-2y}, y > 0 & \text{and} & u_y(x,0) = e^{-3x}, x > 0. \end{cases}$$

We obtain the following solution

.

$$u(x,y) = \int_0^{\infty e^{i\frac{\pi}{4}}} e^{\frac{i}{2}\left[\lambda(x+iy)-\frac{x-iy}{\lambda}\right]} \left(\frac{8\lambda}{\lambda^4-14\lambda^2+1}-\frac{12\lambda}{\lambda^4+34\lambda^2+1}\right) \frac{d\lambda}{\pi}$$



- B. Fornberg and N. Flyer, A numerical implementation of Fokas boundary integral approach: Laplace's equation on a polygonal domain, Proc. R. Soc. A 467, 2983–3003 (2011)
- A.C.L. Ashton, On the rigorous foundations of the Fokas method for linear elliptic partial differential equations, Proc. R. Soc. A 468, 1325–1331 (2012)
- M. Colbrook, A.S. Fokas and P. Hashemzadeh, A hybrid analytical-numerical technique for elliptic PDEs, SIAM J. Sci. Comput., 41(2), A1066-A1090 (2019)
- M. J. Colbrook, N. Flyer and B. Fornberg, On the Fokas method for the solution of elliptic problems in both convex and non-convex polygonal domains. J. Comp. Phys. 374:996-1016 (2018)
- M. J. Colbrook, Extending the unified transform: curvilinear polygons and variable coefficient PDEs, IMA J. Numer. Anal., dry085 (2018)

Water waves - The potential equation

Let the domain Ω_f be defined by

$$\Omega_f = \{ -\infty < x < \infty, ; -h < y < \eta(x,t); t > 0 \}.$$

Irrotational: vorticitity $\gamma = V_x - U_y = 0$. Let ϕ denote the velocity potential, i.e. $\nabla \phi = (U, V)$. The two unknown functions $\eta(x, t)$ and $\phi(x, y, t)$ satisfy the following equations:

$$\begin{split} \Delta \phi &= 0 \quad \text{in} \quad \Omega_f, \\ \phi_y &= 0 \quad \text{on} \quad y = -h, \\ \eta_t + \phi_x \eta_x &= \phi_y \quad \text{on} \quad y = \eta, \\ \phi_t &+ \frac{1}{2} \left(\phi_x^2 + \phi_y^2 \right) + g\eta = 0 \quad \text{on} \quad y = \eta, \end{split}$$

where g is the gravitational acceleration, and h is the constant unperturbed fluid depth.

Introduce q which denotes the value of ϕ on the free surface, i.e.,

$$q(x,t) = \phi\left(x,\eta(x,t),t
ight), \ \ -\infty < x < \infty, \ \ t > 0.$$

The global relation under appropriate transformations, yields a novel non-local equation coupling η and q,

 $\int_{-\infty}^{\infty} e^{ikx} \left\{ i\eta_t \cosh[k(\eta+h)] + q_x \sinh[k(\eta+h)] \right\} dx = 0, \ k \in \mathbb{R}, \ t > 0.$

Furthermore, under the additional assumption of zero surface tension, equation the Bernoulli's law is rewritten

$$q_t + rac{1}{2}(q_x)^2 + g\eta - rac{[\eta_t + q_x\eta_x]^2}{2\left[1 + (\eta_x)^2
ight]} = 0, \quad -\infty < x < \infty, \quad t > 0.$$

Periodic travelling waves

The above equation is a quadratic equation for q', thus we get

$$q' = -c + \sqrt{[1 + (\eta')^2](c^2 - 2g\eta)}.$$

Let $\Omega_p = \{-L < x < L, ; -h < y < \eta(x, t); t > 0\}$, and η and ϕ are 2*L*-periodic functions in *x*. We let $L = \pi$. Then we get

$$\int_{-\pi}^{\pi} e^{ikx} \left[\left(1 - \sqrt{(1 + (\eta')^2) \left(1 - \frac{2g}{c^2} \eta \right)} \right) \sinh(k(\eta + h)) + i\eta' \cosh[k(\eta + h)] \right] dx = 0, \quad \text{for all } k \in \mathbb{Z}$$

Ablowitz, Fokas & Musslimani, On a new non-local formulation of water waves (2006).

Ashton & Fokas, A non-local formulation of rotational water waves (2011). Deconinck & Oliveras, The instability of periodic surface gravity waves (2011). Fokas & Kalimeris, Water waves with moving boundaries (2017).

Additional Applications

- A. S. Fokas, A. A. Himonas, and D. Mantzavinos, The Korteweg–de Vries equation on the half-line. Nonlinearity, 29(2), 489 (2016)
- D. Crowdy, Geometric function theory: a modern view of a classical subject, Nonlinearity 21, 205–219 (2008)
- D.M. Ambrose and D.P. Nicholls, Fokas integral equation for three dimensional layered-media scattering, J. Comput. Phys. 276, 1–25 (2014)
- N.E. Sheils and D.A. Smith, Heat equation on a network using the Fokas method, J. Phys. A 48, 335001 (2015)
- M. Colbrook, L.J. Ayton and A.S. Fokas, The Unified Transform for Mixed Boundary Condition Problems in Unbounded Domains, P. Roy. Soc. Lond. A Mat. 475, 20180605 (2019).
- K. Kalimeris and T. Özsari, An elementary proof of the lack of null controllability for the heat equation on the half line. Applied Math. Letters, 104, 106241 (2020).

From Nonlinear to Linear

$$u(x,t): \qquad iu_t+u_{xx}=0.$$

Rewrite it as the compatibility condition $(M_x)_t - (M_t)_x = 0$, namely

$$\left[e^{i\lambda x+i\lambda^2 t}u\right]_t - i\left[e^{i\lambda x+i\lambda^2 t}(u_x+i\lambda u)\right]_x = 0, \quad \lambda \in \mathbb{C}.$$

By defining $M = e^{i\lambda x + i\lambda^2 t}\mu$, the associated Lax pair consists of the following two linear equations:

$$\mu_{x} + i\lambda\mu = u,$$

$$\mu_{t} + i\lambda^{2}\mu = iu_{x} + \lambda u, \qquad \lambda \in \mathbb{C}.$$

Compare with the classical separation of variables:

$$u(x,t) = X(x;\lambda)T(t;\lambda) \implies \begin{cases} X'' + \lambda^2 X = 0, \\ T' - i\lambda^2 T = 0. \end{cases}$$

A.S. Fokas and I.M. Gelfand, Integrability of linear and nonlinear evolution equations, and the associated nonlinear Fourier transforms (1994)

Asymptotics of the Neumann value for t-periodic data

Example

$$q(0,t)=ae^{i\omega t}+o(1), \quad a,\omega\in\mathbb{R}, \quad t o\infty$$

Claim: For $\lambda = -1$ (focusing NLS)

$$egin{aligned} q_x(0,t) &= c e^{i \omega t} + o(1), \quad t o \infty, \ c &= a \sqrt{\omega - a^2}, \qquad \omega \geq a^2, \end{aligned}$$

or

$$c=ia\sqrt{|\omega|+2a^2}\qquad \omega\leq-6a^2.$$

- J. Lenells and A. S. Fokas. The Nonlinear Schrödinger equation with t-Periodic Data: I. Exact results, Proc. R. Soc. 471, 20140925 (2015)
- J. Lenells, A. S. Fokas, The nonlinear Schrödinger equation with t-periodic data: II. Perturbative results, Proc. R. Soc, 471, 20140926 (2015)

III. The NLS equation - The periodic problem

The NLS equation and its Lax Pair

$$iq_t + q_{xx} - 2\lambda q|q|^2 = 0, \qquad \lambda = \pm 1.$$
 (1)

The NLS equation (1) has a Lax pair given by

$$\mu_x + ik\hat{\sigma}_3\mu = Q\mu, \qquad \mu_t + 2ik^2\hat{\sigma}_3\mu = \tilde{Q}\mu, \qquad (2)$$

$$Q = \begin{pmatrix} 0 & q \\ \lambda \bar{q} & 0 \end{pmatrix}, \qquad \tilde{Q} = 2kQ - iQ_x\sigma_3 - i\lambda|q|^2\sigma_3, \qquad (3)$$

and $\hat{\sigma}_{3}\mu = [\sigma_{3}, \mu]$, with $\sigma_{3} = \text{diag}(-1, 1)$.



THE SPECTRAL FUNCTIONS

$$s(k) = \begin{pmatrix} \overline{a(\overline{k})} & b(k) \\ \lambda \overline{b(\overline{k})} & a(k) \end{pmatrix}, \quad S(k) = \begin{pmatrix} \overline{A(\overline{k})} & B(k) \\ \lambda \overline{B(\overline{k})} & A(k) \end{pmatrix}, \quad S_L(k) = \begin{pmatrix} \overline{A(\overline{k})} & B(k) \\ \lambda \overline{B(\overline{k})} & A(k) \end{pmatrix},$$

where

 $s(k) = \mu_3(0,0,k), \quad S(k) = \mu_1(0,0,k), \quad S_L(k) = \mu_4(L,0,k).$ The entries of the matrices are related by the global relation:

$$(a\mathcal{A} + \lambda \overline{b}e^{2ikL}\mathcal{B})B - (b\mathcal{A} + \overline{a}e^{2ikL}\mathcal{B})A = e^{4ik^2T}c^+(k), \qquad k \in \mathbb{C}, \quad (4)$$

where

$$c^+(k) = O\left(\frac{1}{k}\right) + O\left(\frac{e^{2ikL}}{k}\right), \qquad k \to \infty, \ k \in \mathbb{C}.$$
 (5)

The above functions satisfy the unit determinant relations

$$a\bar{a} - \lambda b\bar{b} = 1, \qquad A\bar{A} - \lambda B\bar{B} = 1, \qquad A\bar{A} - \lambda B\bar{B} = 1.$$
 (6)

The functions *a* and *b* satisfy

$$a(k) = 1 + O\left(\frac{1}{k}\right) + O\left(\frac{e^{2ikL}}{k}\right), \quad b(k) = O\left(\frac{1}{k}\right) + O\left(\frac{e^{2ikL}}{k}\right), \qquad k \to \infty,$$

whereas the functions A and B satisfy

$$A(k) = 1 + O\left(\frac{1}{k}\right) + O\left(\frac{e^{4ik^2T}}{k}\right), \quad B(k) = O\left(\frac{1}{k}\right) + O\left(\frac{e^{4ik^2T}}{k}\right), \qquad k \to \infty.$$

THE RH PROBLEM FOR THE PERIODIC CASE

q(0,t) = q(L,t) and $q_x(0,t) = q_x(L,t)$ for $t \in [0,T]$. (7)



In this case A = A and B = B. The jump matrices:

$$J_{1} = \begin{pmatrix} \delta/d & -Be^{2ikL}e^{-2i\theta} \\ \lambda \bar{B}e^{2i\theta}/(d\alpha) & a/\alpha, \end{pmatrix} \qquad J_{2} = \begin{pmatrix} 1 & -\beta e^{-2i\theta}/\bar{\alpha} \\ \lambda \bar{\beta}e^{2i\theta}/\alpha & 1/(\alpha\bar{\alpha}) \end{pmatrix},$$
$$J_{3} = \begin{pmatrix} \bar{\delta}/\bar{d} & -Be^{-2i\theta}/(\bar{d}\bar{\alpha}) \\ \lambda \bar{B}e^{-2ikL}e^{2i\theta} & \bar{a}/\bar{\alpha} \end{pmatrix}, \quad J_{4} = J_{3}J_{2}^{-1}J_{1}, \qquad (8)$$

where

 $\alpha = aA + \lambda \bar{b}Be^{2ikL}, \quad \beta = bA + \bar{a}Be^{2ikL}, \quad d = a\bar{A} - \lambda b\bar{B}, \quad \delta = \alpha \bar{A} - \lambda \beta \bar{B}.$ The global relation (4) becomes

$$\lambda \bar{b} e^{2ikL} B^2 + (a - \bar{a} e^{2ikL}) AB - bA^2 = e^{4ik^2 T} c^+.$$
(9)

THE NEW RH PROBLEM INVOLVING

$$\Gamma(k) = \frac{B(k)}{A(k)}$$
 and $m = MH$,

where the sectionally meromorphic function H is defined by

$$H_1 = \begin{pmatrix} A & 0 \\ 0 & 1/A \end{pmatrix}, \qquad H_2 = H_3 = I, \qquad H_4 = \begin{pmatrix} 1/\bar{A} & 0 \\ 0 & \bar{A} \end{pmatrix}.$$

Then, we formulate the new RH problem with the jump functions:

$$\begin{split} v_{1} &= \begin{pmatrix} \frac{a - \lambda b \bar{\Gamma} - \lambda \Gamma (\bar{a} \bar{\Gamma} - \bar{b}) e^{2ikL}}{\lambda \bar{\Gamma} e^{2i\theta}} & -\Gamma e^{2ikL} e^{-2i\theta} \\ \frac{\lambda \bar{\Gamma} e^{2i\theta}}{(a - \lambda b \bar{\Gamma})(a + \lambda b \bar{\Gamma} e^{2ikL})} & \frac{a}{a + \lambda b \bar{\Gamma} e^{2ikL}} \end{pmatrix}, \qquad \text{arg } k = \frac{\pi}{2}, \\ v_{2} &= \begin{pmatrix} 1 - \lambda \Gamma \bar{\Gamma} & -\frac{(\bar{a} \Gamma e^{2ikL} + b) e^{-2i\theta}}{\bar{a} + \lambda b \bar{\Gamma} e^{-2ikL}} \\ \frac{\lambda (a \bar{\Gamma} e^{-2ikL} + \bar{b}) e^{2i\theta}}{a + \lambda \bar{b} \Gamma e^{2ikL}} & \frac{1}{(a + \lambda \bar{b} \Gamma e^{-2ikL})(\bar{a} + \lambda b \bar{\Gamma} e^{-2ikL})} \end{pmatrix}, \qquad \text{arg } k = 0, \\ v_{3} &= \begin{pmatrix} \frac{\bar{a} - \lambda \bar{b} \Gamma - \lambda \bar{\Gamma} (a \Gamma - b) e^{-2ikL}}{\bar{a} - \lambda \bar{b} \Gamma} & -\frac{\Gamma e^{-2i\theta}}{\bar{a} + \lambda b \bar{\Gamma} e^{-2ikL}} \\ \lambda \bar{\Gamma} e^{-2ikL} e^{2i\theta} & \frac{\bar{a} - \lambda \bar{b} \Gamma}{\bar{a} - \lambda \bar{b} \Gamma} & -\frac{(a \Gamma - b) e^{-2ikL}}{\bar{a} + \lambda b \bar{\Gamma} e^{-2ikL}} \end{pmatrix}, \qquad \text{arg } k = -\frac{\pi}{2}, \\ v_{4} &= \begin{pmatrix} \frac{1 - \lambda \Gamma \bar{\Gamma}}{(a - \lambda b \bar{\Gamma})(\bar{a} - \lambda \bar{b} \Gamma)} & -\frac{(a \Gamma - b) e^{-2i\theta}}{\bar{a} - \lambda \bar{b} \Gamma} \\ \frac{\lambda (\bar{a} \bar{\Gamma} - \bar{b}) e^{2i\theta}}{a - \lambda \bar{b} \Gamma} & 1 \end{pmatrix}, \qquad \text{arg } k = \pi. \end{split}$$

THE FINAL RH PROBLEM

We define the function $\tilde{\Gamma}(k)$ by

$$\tilde{\Gamma} = \frac{\lambda}{2e^{ikL}\bar{b}} \Big(\bar{a}e^{ikL} - ae^{-ikL} - i\sqrt{4-\Delta^2}\Big), \tag{10}$$

where $\Delta(k)$ is given by

$$\Delta = a e^{-ikL} + \bar{a} e^{ikL}, \qquad k \in \mathbb{C}.$$
(11)

We introduce the transform

$$\tilde{m} = mg,$$
 (12)

where the function g(k) is given by

$$g_{1} = \begin{pmatrix} \frac{a + \lambda \bar{b} \bar{\Gamma} e^{2ikL}}{a + \lambda \bar{b} \bar{\Gamma} e^{2ikL}} & (\bar{\Gamma} - \Gamma) e^{2ikL} e^{-2i\theta} \\ 0 & \frac{a + \lambda \bar{b} \bar{\Gamma} e^{2ikL}}{a + \lambda \bar{b} \bar{\Gamma} e^{2ikL}} \end{pmatrix}, \qquad g_{2} = \begin{pmatrix} 1 & 0 \\ \frac{\lambda (\bar{\Gamma} - \bar{\Gamma}) e^{2i\theta}}{(a - \lambda b \bar{\Gamma})(a - \lambda b \bar{\Gamma})} & 1 \end{pmatrix}, \\ g_{3} = \begin{pmatrix} 1 & \frac{(\bar{\Gamma} - \Gamma) e^{-2i\theta}}{(\bar{a} - \lambda \bar{b} \bar{\Gamma})(\bar{a} - \lambda \bar{b} \bar{\Gamma})} \\ 0 & 1 \end{pmatrix}, \qquad g_{4} = \begin{pmatrix} \frac{\bar{a} + \lambda b \bar{\bar{\Gamma}} e^{-2ikL}}{\bar{a} + \lambda b \bar{\Gamma} e^{-2ikL}} & 0 \\ \lambda (\bar{\bar{\Gamma}} - \bar{\Gamma}) e^{-2ikL} e^{2i\theta} & \frac{\bar{a} + \lambda b \bar{\Gamma} e^{-2ikL}}{\bar{a} + \lambda b \bar{\Gamma} e^{-2ikL}} \end{pmatrix},$$

where g_j denotes the restriction of g to D_j for $j = 1, \ldots, 4$.



The functions \tilde{v}_{j} are identical to the v_{j} , with the substitution Γ to $\tilde{\Gamma}$ and $\tilde{V}_{D_{1}}^{\text{cut}} = \begin{pmatrix} \frac{a+\lambda \tilde{b}\tilde{\Gamma} + e^{2ikL}}{a+\lambda \tilde{b}\tilde{\Gamma} - e^{2ikL}} & (\tilde{\Gamma}_{-} - \tilde{\Gamma}_{+})e^{2ikL}e^{-2i\theta} \\ 0 & \frac{a+\lambda \tilde{b}\tilde{\Gamma} - e^{2ikL}}{a+\lambda \tilde{b}\tilde{\Gamma} + e^{2ikL}} \end{pmatrix}$, $\tilde{v}_{D_{2}}^{\text{cut}} = \begin{pmatrix} 1 & 0 \\ \frac{\lambda(\tilde{\Gamma} - \tilde{\Gamma}_{+})e^{-2i\theta}}{(a-\lambda \tilde{b}\tilde{\Gamma}_{-})(a-\lambda \tilde{b}\tilde{\Gamma}_{+})} \\ 1 \end{pmatrix}$, $\tilde{v}_{D_{3}}^{\text{cut}} = \begin{pmatrix} 1 & 0 \\ \frac{\lambda(\tilde{\Gamma} - \tilde{\Gamma}_{+})e^{-2i\theta}}{(\tilde{a}-\lambda \tilde{b}\tilde{\Gamma}_{-})(\tilde{a}-\lambda \tilde{b}\tilde{\Gamma}_{+})} \\ 0 & 1 \end{pmatrix}$, $\tilde{v}_{D_{3}}^{\text{cut}} = \begin{pmatrix} \frac{\tilde{a}+\lambda \tilde{b}\tilde{\Gamma} - e^{-2ikL}}{(\tilde{a}-\lambda \tilde{b}\tilde{\Gamma}_{-})(\tilde{a}-\lambda \tilde{b}\tilde{\Gamma}_{+})} \\ 0 & 1 \end{pmatrix}$, $\tilde{v}_{2}^{\text{cut}} = \tilde{v}_{D_{3}}^{\text{cut}} \tilde{v}_{2-},$ $\tilde{v}_{4}^{\text{cut}} = \tilde{v}_{D_{3}}^{\text{cut}} \tilde{v}_{4-},$

$$\tilde{v}_{D_4}^{\rm cut} = \begin{pmatrix} \overline{a_{\pm\lambda}b\bar{\tilde{\Gamma}}_{\pm}e^{-2ikL}} & 0\\ \lambda(\overline{\tilde{\Gamma}}_{-} - \overline{\tilde{\Gamma}}_{\pm})e^{2i\theta}e^{-2ikL} & \frac{\bar{a}_{\pm\lambda}b\bar{\tilde{\Gamma}}_{\pm}e^{-2ikL}}{\bar{a}_{\pm\lambda}b\bar{\tilde{\Gamma}}_{\pm}e^{-2ikL}} \end{pmatrix},$$

AN EXPLICIT EXAMPLE

Initial data:

$$q(x,0) = q_0 e^{\frac{2i\pi N}{L}x}, \qquad q_0 > 0, \quad N \in \mathbb{Z}, \qquad x \in [0,L].$$
 (13)

Then, via the analysis of the RH we obtain the solution

$$q(x,t) = q_0 e^{\frac{2i\pi N}{L}x} e^{-2i\lambda q_0^2 t - \frac{4i\pi^2 N^2}{L^2}t}.$$
 (14)

The spectral functions *a* and *b*:

$$a(k) = \frac{e^{i(kL+\pi N)}(Lr\cos(Lr) - i(kL + \pi N)\sin(Lr))}{Lr}, \ b(k) = -\frac{q_0e^{i(kL+\pi N)}\sin(Lr)}{r},$$

where r(k) denotes the square root

$$r(k) = \sqrt{\left(k + \frac{\pi N}{L}\right)^2 - \lambda q_0^2}$$

It follows that

$$\Delta(k) = 2(-1)^N \cos(Lr(k)).$$

The periodic spectrum is given by the two simple zeros

$$\lambda^{\pm} = \begin{cases} -\frac{\pi N}{L} \pm q_0 & \text{if } \lambda = 1, \\ -\frac{\pi N}{L} \pm i q_0 & \text{if } \lambda = -1. \end{cases}$$

 Δ also has the following infinite sequence of double zeros

$$-\frac{\pi N}{L} \pm \sqrt{\frac{n^2 \pi^2}{L^2} + \lambda q_0^2}, \qquad n \in \mathbb{Z} \setminus \{0\}.$$

Thus,

$$\sqrt{4-\Delta^2}=2(-1)^N\sin(Lr)$$
 and $\widetilde{\Gamma}(k)=-rac{\lambda i(k-r+rac{\pi N}{L})}{q_0}.$

...

THE RH PROBLEM For $N \ge 1$, the RH problem can be formulated as follows.



The jump contour and jump matrices for $\lambda = 1$ (left) and $\lambda = -1$ (right).

THE JUMP FUNCTIONS $\tilde{\mathbf{v}}_{1} = \begin{pmatrix} \frac{2\lambda r(k-r+\frac{\pi N}{L})}{q_{0}^{2}} & \frac{i\lambda(k-r+\frac{\pi N}{L})e^{-2i(\theta-kL)}}{q_{0}}\\ \frac{i(k-r+\frac{\pi N}{L})e^{2i(\theta-kL+Lr)}}{q_{0}} & \frac{(k+\frac{\pi N}{L})(1-e^{2iLr})+r(1+e^{2iLr})}{2r} \end{pmatrix}, \qquad k \in i\mathbb{R}_{+},$ $\tilde{\mathbf{v}}_{2} = \begin{pmatrix} \frac{2\lambda r(k-r+\frac{\pi N}{L})}{q_{0}^{2}} & \frac{i\lambda(k-r+\frac{\pi N}{L})e^{-2i(\theta-kL+Lr)}}{q_{0}} \\ \frac{i(k-r+\frac{\pi N}{L})e^{2i(\theta-kL+Lr)}}{r} & \mathbf{1} \end{pmatrix},$ $k \in \mathbb{R}_+ \setminus \mathcal{C},$ $\tilde{\mathbf{v}}_{3} = \begin{pmatrix} \frac{2\lambda r(k-r+\frac{\pi N}{L})}{q_{0}^{2}} & \frac{i\lambda(k-r+\frac{\pi N}{L})e^{-2i(\theta-kL+Lr)}}{q_{0}}\\ \frac{i(k-r+\frac{\pi N}{L})e^{2i(\theta-kL)}}{q_{0}} & \frac{(k+\frac{\pi N}{L})(1-e^{-2iLr})+r(1+e^{-2iLr})}{2r} \end{pmatrix}, \qquad k \in i\mathbb{R}_{-},$ $\tilde{v}_4 = \begin{pmatrix} \frac{2\lambda r(k-r+\frac{\pi N}{L})}{q_0^2} & \frac{i\lambda(k-r+\frac{\pi N}{L})e^{-2i(\theta-kL)}}{q_0} \\ \frac{i(k-r+\frac{\pi N}{L})e^{2i(\theta-kL)}}{q_0} & 1 \end{pmatrix}, \qquad k \in \mathbb{R}_- \setminus \mathcal{C}.$ Let $\mathfrak{r}(k) = \sqrt{|(k + \pi N/L)^2 - \lambda q_0^2|} \ge 0, \qquad \lambda \pm 1.$ For $\lambda = 1$ (left column), and $\lambda = -1$ (right column): $\tilde{v}_2^{\mathsf{cut}} = \begin{pmatrix} 0 & \frac{i(k-i\mathfrak{r}(k)+\frac{\pi N}{L})e^{-2i(\theta-kL)}}{q_0} \\ \frac{i(k+i\mathfrak{r}(k)+\frac{\pi N}{L})e^{2i(\theta-kL)}}{q_0} & e^{-2L\mathfrak{r}(k)} \end{pmatrix}, \quad \tilde{v}_{D_2}^{\mathsf{cut}} = \begin{pmatrix} 1 & 0 \\ \frac{2i\mathfrak{r}(k)e^{2i(\theta-kL)}}{q_0} & 1 \end{pmatrix},$ $\tilde{v}_4^{\text{cut}} = \begin{pmatrix} 0 & \frac{i(k+i\mathfrak{r}(k)+\frac{\pi N}{L})e^{-2i(\theta-kL)}}{q_0} \\ \frac{i(k-i\mathfrak{r}(k)+\frac{\pi N}{L})e^{2i(\theta-kL)}}{1} & 1 \end{pmatrix}, \quad \tilde{v}_{D_3}^{\text{cut}} = \begin{pmatrix} 1 & -\frac{2i\mathfrak{r}(k)e^{-2i(\theta-kL)}}{q_0} \\ 0 & 1 \end{pmatrix}$